

2.5 Tangent Vectors

Consider two curves, $X_1^\mu(u)$ and $X_2^\mu(u)$

The curves are tangent at $u = u_0$ if:

1. They meet. $X_1^\mu(u_0) = X_2^\mu(u_0)$
2. They touch, i.e. they don't cross. $\frac{dX_1^\mu}{du}(u_0) = \frac{dX_2^\mu}{du}(u_0)$

The tangent vector to the curve at some point P with $u = u_0$ is defined to be

$$T^\mu = \frac{dX^\mu}{du}.$$

A congruence is defined to be a set of curves such that each point in the manifold lies on exactly one curve, e.g. lines of latitude on a sphere S^2 .

In another coordinate system,

$$T'^\mu = \frac{dX'^\mu}{du} = \frac{\partial X'^\mu}{\partial X^\nu} \frac{dX^\nu}{du} = J^\mu_\nu T^\nu$$

The tangent vectors “live” in the tangent space $T_p(M)$. (P stands for plane, M for manifold). Note that this tangent space depends on where you are on the manifold.

2.6 Vectors, Co-Vectors and Tensors

Any n-tuple (array of numbers) which transform like a tangent vector is a member of $T_p(M)$ and is called a vector. i.e. anything which transforms according to the rules

$$A'^\mu = J^\mu_\nu A^\nu \text{ and } A^\mu = J^\mu_\nu A'^\nu$$

is a vector. It can, and generally does, depend on position.

NB: vectors are defined at a point in M and can be thought of as a map $T_p(M) \rightarrow \mathfrak{R}$.

If A^μ and B^μ are vectors defined at some point P , then consider adding those vectors together $C^\mu = \alpha A^\mu + \beta B^\mu$:

$C'^\mu = \alpha A'^\mu + \beta B'^\mu$ by definition.

$$C'^\mu = \alpha J^\mu_\nu A^\nu + \beta J^\mu_\nu B^\nu$$

As both vectors are at the same point, both J^μ_ν 's are the same.

$$\begin{aligned} C'^\mu &= J^\mu_\nu [\alpha A^\nu + \beta B^\nu] \\ &= J^\mu_\nu C^\nu \end{aligned}$$

Hence C^μ is also a vector at P.

Geometrically, we have shown that the tangent space $T_p(M)$ is a vector space (i.e. a space which allows the linear addition of vectors within in).

If $\phi = A_\mu B^\mu$ is a scalar for all vectors B^μ , then A_μ is a covector.

NB: in many books, including D'Inverno, covectors are called covariant vectors, and vectors are called contravariant vectors.

The question is how does A_μ transform under coordinate rotation?

We know that $\phi' = \phi$ because ϕ is a scalar.

$$A'_\mu B'^\mu = \phi' = \phi = A_\mu B^\mu$$

$$A'_\mu J'^\mu_\alpha B^\alpha = A_\alpha B^\alpha$$

$$(A'_\mu J'^\mu_\alpha - A_\alpha) B^\alpha = 0$$

As this is true for all vectors B^α , we can use

$$B^\alpha = \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ \vdots \\ 0 \end{pmatrix}, \dots$$

hence:

$$A'_\mu J'^\mu_\alpha - A_\alpha = 0$$

$$\rightarrow A'_\mu = J^\alpha_\mu A_\alpha$$

It is easy to show that:

1. $g_{\mu\nu} A^\nu$ is a covector
2. $g^{\mu\nu} B_\nu$ is a vector

Hence we call $A_\mu = g_{\mu\nu} A^\nu$ and $B^\mu = g^{\mu\nu} B_\nu$. So the metric and its inverse can be used to raise and lower indices.

The vectors live in the tangent space $T_p(M)$ of the manifold M , and the covectors live in the dual-space $T_p^*(M)$. This space is geometrically orthogonal to $T_p(M)$.

Note: vectors and covectors are defined as some point in the manifold. One can add vectors together if they are defined at the same point since $T_p(M)$ and $T_p^*(M)$ are vector spaces. But one cannot do this if they are defined at different points.

We now generalize and define an $\binom{a}{b}$ tensor at some point P in M to be a map

$$\underbrace{T_p(\mu) \times \dots \times T_p(\mu)}_a \times \underbrace{T_p^*(\mu) \times \dots \times T_p^*(M)}_b \rightarrow R$$

which transforms according to:

$$A'^{\mu_1 \dots \mu_a}_{\nu_1 \dots \nu_b} = \underbrace{J'^{\mu_1}_{\alpha_1} \dots J'^{\mu_a}_{\alpha_a}}_a \underbrace{J^{\beta_1}_{\nu_1} \dots J^{\beta_b}_{\nu_b}}_b A^{\alpha_1 \dots \alpha_a}_{\beta_1 \dots \beta_b}$$

e.g. special cases:

- Vectors are $\binom{1}{0}$ tensors
- Covectors are $\binom{0}{1}$ tensors
- Scalars are $\binom{0}{0}$ tensors
- $g_{\mu\nu}$ is a $\binom{0}{2}$ tensor
- $g^{\mu\nu}$ is a $\binom{2}{0}$ tensor
- δ^μ_ν is a $\binom{1}{1}$ tensor.

Important points:

1. If $A^{\mu_1 \dots \mu_a}_{\nu_1 \dots \nu_a} = B^{\mu_1 \dots \mu_a}_{\nu_1 \dots \nu_a}$ is true in one coordinate system or frame, then it is true in all.
2. If $A^{\mu_1 \dots \mu_a}_{\nu_1 \dots \nu_a} = 0$ in one frame, it is zero in all.
3. Two terms of the same “type” can be added together at some point P in M .
If A and B are $\begin{pmatrix} 2 \\ 0 \end{pmatrix}$ tensors, then $C^{\mu\nu} = A^{\mu\nu} + B^{\mu\nu}$ is a tensor of type $\begin{pmatrix} 2 \\ 0 \end{pmatrix}$.

Proof:

$$\begin{aligned} C^{\mu\nu} &= A^{\mu\nu} + B^{\mu\nu} \\ &= J^{\mu}_{\alpha} J^{\nu}_{\beta} A^{\alpha\beta} + J^{\mu}_{\alpha} J^{\nu}_{\beta} B^{\alpha\beta} \end{aligned}$$

This is true because $A^{\mu\nu}$ and $B^{\mu\nu}$ are tensors.

$$\begin{aligned} C^{\mu\nu} &= J^{\mu}_{\alpha} J^{\nu}_{\beta} (A^{\alpha\beta} + B^{\alpha\beta}) \\ &= J^{\mu}_{\alpha} J^{\nu}_{\beta} C^{\alpha\beta} \end{aligned}$$

$\rightarrow C^{\mu\nu}$ is a $\begin{pmatrix} 2 \\ 0 \end{pmatrix}$ tensor.

4. If $C = AB$, where A is a tensor of type $\begin{pmatrix} a \\ b \end{pmatrix}$ and B is a tensor of type $\begin{pmatrix} c \\ d \end{pmatrix}$, then C is a tensor of type $\begin{pmatrix} a+c \\ b+d \end{pmatrix}$.

$$C^{\mu_1 \dots \mu_a \alpha_1 \dots \alpha_c}_{\nu_1 \dots \nu_a \beta_1 \dots \beta_d} = A^{\mu_1 \dots \mu_a}_{\nu_1 \dots \nu_a} B^{\alpha_1 \dots \alpha_c}_{\beta_1 \dots \beta_d}$$

See Questions Sheet 2, Number 6.

5. A tensor of type $\begin{pmatrix} a \\ b \end{pmatrix}$ becomes of type $\begin{pmatrix} a-2 \\ b \end{pmatrix}$ upon contraction with the metric, and of type $\begin{pmatrix} a \\ b-2 \end{pmatrix}$ when contracted with the inverse metric.

e.g. $T^{\mu\nu\rho}_{\alpha\beta}$ which is a $\begin{pmatrix} 3 \\ 2 \end{pmatrix}$ tensor, then $g_{\mu\nu} T^{\mu\nu\rho}_{\alpha\beta}$ is of type $\begin{pmatrix} 1 \\ 2 \end{pmatrix}$ and $g^{\alpha\beta} T^{\mu\nu\rho}_{\alpha\beta}$ is of type $\begin{pmatrix} 3 \\ 0 \end{pmatrix}$.

6. One can define the inner product of two vectors T^{μ} and S^{ν} to be $d(S, T) = S_{\mu} T^{\mu} = g_{\mu\nu} T^{\mu} S^{\nu}$ which is a scalar.

The length of a vector is $\|T\| = (d(T, T))^{\frac{1}{2}}$, and the angle between S and T is

defined by $\cos \theta = \frac{d(T, S)}{\|T\| \|S\|}$.

Notation

Symmetrization and antisymmetrization

We will from time to time use the permutation of indices:

$()$ will mean Symmetrization

$[]$ will mean antisymmetrization.

e.g.:

1. $\begin{pmatrix} 0 \\ 2 \end{pmatrix}$ tensor $A_{\mu\nu}$:

$$A_{(\mu\nu)} = \frac{1}{2} (A_{\mu\nu} + A_{\nu\mu})$$

$$A_{[\mu\nu]} = \frac{1}{2} (A_{\mu\nu} - A_{\nu\mu})$$

2. $\binom{0}{3}$ tensor $A_{\mu\nu\rho}$

$$A_{(\mu\nu\rho)} = \frac{1}{3!} [A_{\mu\nu\rho} + A_{\rho\mu\nu} + A_{\nu\rho\mu} + A_{\nu\mu\rho} + A_{\rho\nu\mu} + A_{\mu\rho\nu}]$$

$$A_{[\mu\nu\rho]} = \frac{1}{3!} [A_{\mu\nu\rho} + A_{\rho\mu\nu} + A_{\nu\rho\mu} - A_{\nu\mu\rho} - A_{\rho\nu\mu} - A_{\mu\rho\nu}]$$

(Cyclic permutations, minus the anticyclic permutations)

Consider a few examples:

1.

$$\begin{aligned} A_{(\mu\nu\rho)} x^\mu x^\nu x^\rho &= \frac{1}{3!} [A_{\mu\nu\rho} + A_{\rho\mu\nu} + A_{\nu\rho\mu} + A_{\mu\rho\nu} + A_{\nu\mu\rho} + A_{\rho\nu\mu}] x^\mu x^\nu x^\rho \\ &= A_{\mu\nu\rho} x^\mu x^\nu x^\rho \end{aligned}$$

2. $A_{[\mu\nu\rho]} x^\mu x^\nu x^\rho = 0$

3.

$$\begin{aligned} A_{(\mu\nu)} A^{[\mu\nu]} &= \frac{1}{2} (A_{\mu\nu} + A_{\nu\mu}) \frac{1}{2} (A^{\mu\nu} - A^{\nu\mu}) \\ &= \frac{1}{4} A_{\mu\nu} A^{\mu\nu} + A_{\nu\mu} A^{\mu\nu} - A_{\mu\nu} A^{\nu\mu} - A_{\nu\mu} A^{\nu\mu} \\ &= 0 \end{aligned}$$

2.7 Conformal Metrics

Two metrics $g_{\mu\nu}$ and $G_{\mu\nu}$ are conformally related if there exists a possibly spatially dependant function $\Omega(X^{\mu\nu})$ such that

$$G_{\mu\nu} = \Omega^2 g_{\mu\nu}$$

This is of interest because:

1. $ds_g^2 = g_{\mu\nu} dx^\mu dx^\nu$

$$ds_G^2 = G_{\mu\nu} dx^\mu dx^\nu$$

$$\text{Hence } ds_G^2 = \Omega^2 ds_g^2$$

\rightarrow the null curves ($ds^2 = 0$) of both metrics are the same.

2. Consider two vectors A^μ and B^μ , then the angle between them is

$$\cos \theta_g = \frac{g_{\mu\nu} A^\mu B^\nu}{(g_{\mu\nu} A^\mu A^\nu)^{1/2} (g_{\mu\nu} B^\mu B^\nu)^{1/2}}$$

$$\cos \theta_G = \frac{G_{\mu\nu} A^\mu B^\nu}{(G_{\mu\nu} A^\mu A^\nu)^{1/2} (G_{\mu\nu} B^\mu B^\nu)^{1/2}}$$

$$\rightarrow \cos \theta_G = \cos \theta_g$$

So conformal transformations preserve angles.